

# Firearms & Tool Marks

## Bullet Comparison

### Introduction

The goal is to determine if an 'unknown' bullet found at a potential crime scene has been fired with a specific firearm. Firearms leave characteristic marks on the bullets they fire, so firing a second 'known' bullet and comparing the marks can be used to link the firearm with a specific event.

Specifically, fired bullets have a number of land-engraved areas (land impressions) that depend on the barrel rifling (Figure 1). To guarantee a true match, all of these impressions have to match in both form and in sequence around both bullets.

The task is thus to measure the land impressions and match them up from one



Figure 1. Impressions left on a Beretta bullet.

bullet to the other (Table A). If a full match is not possible, the bullets were perhaps not fired from the same firearm.



Figure 2. Fired Beretta bullets have six land impressions that are analysed to find a match in both form and sequence.

		Know Bullet (B1)					
		B1L1	B1L2	B1L3	B1L4	B1L5	B1L6
Unknown Bullet 1 (U1)	U1L1						
	U1L2						
	U1L3						
	U1L4						
	U1L5						
	U1L6						

Table A. Ideal land impression matches between two bullets, well known (B1) and unknown (U1).

# Firearms & Tool Marks

## Bullet Comparison

### Establishing a match between two land impressions

The Alabama Department of Forensic Sciences (ADFS) has developed a method for comparing land impressions using the PLu neox and the SensoMAP software (Premium Edition) and the Sensofar Forensic Module<sup>1</sup>. The steps are:

1 Measure an extended topography, about 1mm wide and the full length of the land impression (Figure 3).

2 A region of interest (ROI) is selected and individual characteristics of the surface are obtained by filtering (Figure 4).

3 A profile is extracted and both bullets are compared directly (Figure 4).

a Compute the Cross-Correlation Function (CCF). The key parameter is  $CCF_{MAX}$ , which is one if the two profiles are identical. For the two profiles shown in Figure 4 the value of  $CCF_{MAX}$  is 0.957.

b Compute the Signature Difference ( $D_s$ ):

$$D_s = R'_Q{}^2 / R_Q{}^2$$

This parameter was proposed by NIST for quantifying signature differences.  $R'_Q$  is the roughness of the difference between mean profiles (bullet 1 and 2) and  $R_Q$  is the roughness from bullet 1. If the two profiles are exactly the same,  $D_s$  is obviously zero, but it increases with mounting discrepancy between the two.

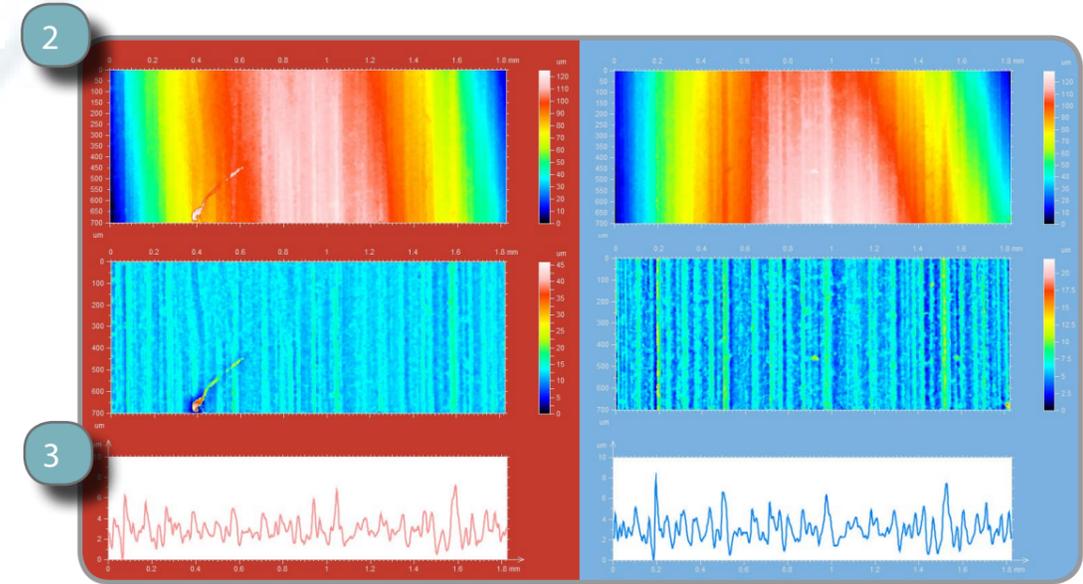


Figure 4. SensoMAP data processing on both scanned areas for bullet 1 and 2.

	B1L1	B1L2	B1L3	B1L4	B1L5	B1L6
	B2L1	B2L2	B2L3	B2L4	B2L5	B2L6
$CCF_{MAX}$	0.957	0.896	0.902	0.855	0.896	0.949
$D_s(\%) (k)$	11.4	17.2	57.5	67.0	26.8	22.8

Table B. Similarity parameters for two known bullets.

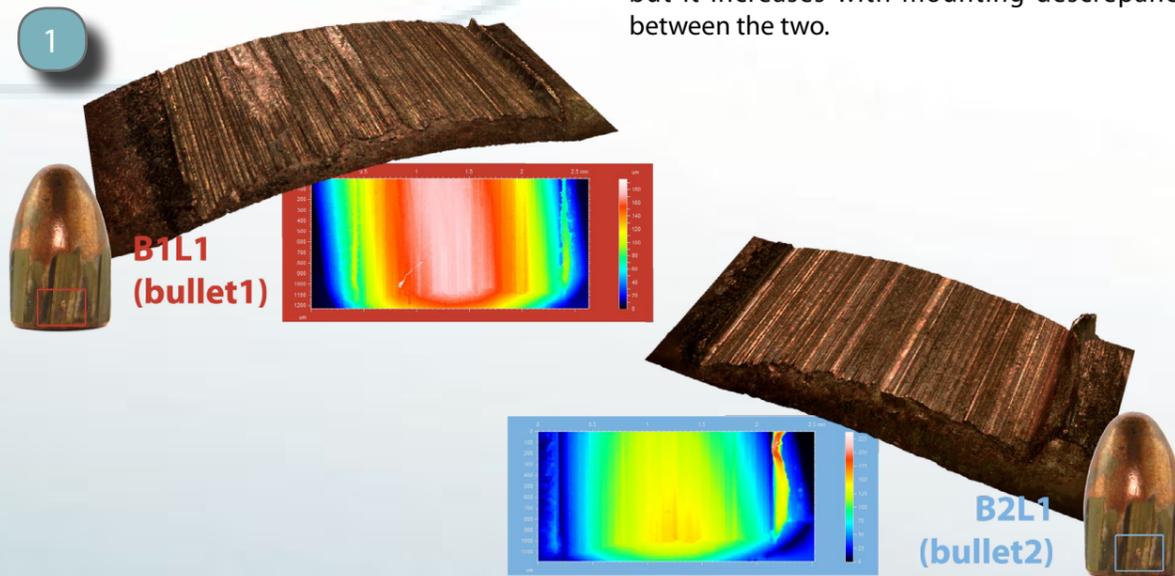


Figure 3. Land impression and scanned regions on two bullets fired with the same firearm.

Step 3 on figure 4 shows profiles extracted from measurements obtained on matching land impressions of two bullets known to be fired from the same firearm. NIST has developed two reliable parameters to describe the degree of similarity<sup>2,3</sup>:

Table B lists the values  $CCF_{MAX}$  and  $D_s$  for all (in this case) six land impressions on two known bullets. For the profiles in Figure 4 (B1L1 and B2L1)  $CCF_{MAX}$  is 0.957 and  $D_s$  is 11.4%. Note that  $CCF_{MAX}$  is high for other pairs of profiles shown in the table while  $D_s$  has larger variability.

### Comparing unknown profiles

These values are now used to compare one single land impression of a known bullet to all land impressions of an unknown bullet. Figure 5 shows a contour rendering of six pairs of profiles, where the known profile is plotted to the left of every unknown profile. The known profile corresponding to the land impression B1L1 best matches the unknown profile

corresponding to the land impression U1L1.

A comparison of the two parameters CCF and  $D_s$  for the matching and non-matching land impressions confirms this conclusion (Table C). The land impression where the differences are smaller is L1 and for the other land impressions the differences are very high.

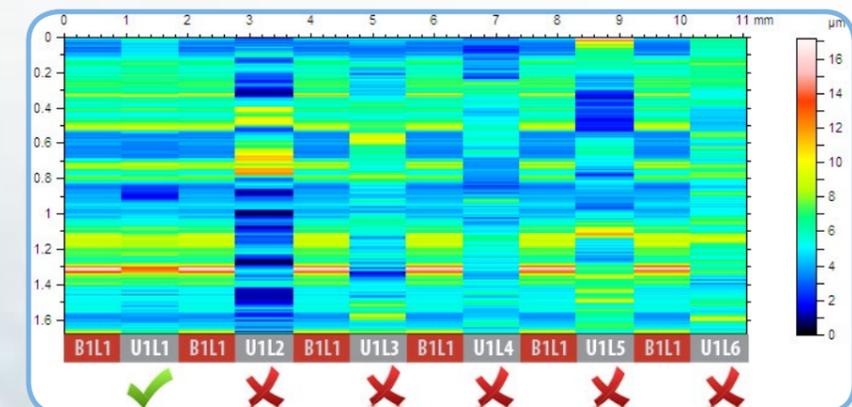


Figure 5. Comparison of a known profile (B1) to a set of unknown profiles (U1).

	B1L1					
	U1L1	U1L2	U1L3	U1L4	U1L5	U1L6
<b>CCF</b>	<b>0.915</b>	<b>0.706</b>	<b>0.752</b>	<b>0.602</b>	<b>0.773</b>	<b>0.727</b>
Difference from CFF <sub>MAX</sub>	<b>0.042</b>	<b>0.196</b>	<b>0.144</b>	<b>0.253</b>	<b>0.123</b>	<b>0.252</b>
<b>D<sub>SU</sub> (%)</b>	<b>11.4</b>	<b>130</b>	<b>67.0</b>	<b>346</b>	<b>49.8</b>	<b>107</b>
Difference from D <sub>S</sub> (k)	<b>0.0</b>	<b>72.5</b>	<b>49.8</b>	<b>279</b>	<b>23</b>	<b>84.2</b>

**Table C.** CCF and D<sub>s</sub> values for the matching and non-matching land impressions.

## Conclusions

1 3D optical comparative measurements assist with confirming casework determinations made using traditional analysis such as comparison microscopy

2 PLu neox instrument, SensoMAP software and Sensofar Forensic Module are a complete solution. You can use confocal techniques to

obtain the most accurate 3D measurements and state of the art software to automatically calculate key analysis parameters such as CCF and D<sub>s</sub>

3 It is possible to add objectivity to Firearms and Tool Marks analyses by using 3D Confocal Microscopy Measurements.

<sup>1</sup> D. S. McClarin, D. Stella: 'The 10 Consecutive Ruger Barrel Study: A 3D look using the PLu neox from Sensofar', 2nd Annual AFTE Training Seminar, Chicago, May 2011

<sup>2</sup> L. Ma, J. Song, E. Whitenton, A. Zheng, T. Vorburger and J. Zhou: 'NIST bullet signature measurement system for SMR (Standard Reference Material) 2460 standard bullets', J. Forensic Sci., 49, No. 4, July 2004, pp. 649-659

<sup>3</sup> J. Song, T. Vorburger, L. Ma, J. Libert and S. Ballou: 'A metric for the comparison of surface topographies of standard reference material (SMR) bullets and casings', 2005

**SENSOFAR** is a leading-edge technology company operating at the highest quality standards within the field of non-contact surface metrology. We provide high-accuracy optical profilers based on interferometry and confocal techniques. From standard setups for R&D and quality inspection laboratories, to complete non contact metrology solutions for online production processes, Sensofar is offering a technology enabling our customers to achieve the most challenging breakthroughs, particularly in semiconductor, precision optics, data storage, display devices, thick and thin films and material testing technologies, in more than 15 countries through Channel Partners and with own office in Shanghai and USA.



Headquarters and sales office  
**SENSOFAR METROLOGY**, Parc Audiovisual Catalunya  
 Ctra. BV1274, km 1 - 08225 **TERRASSA** (SPAIN)  
 Tel. (+34) **93 700 14 92** - Fax (+34) 93 786 01 16  
 info@sensofar.com - [www.sensofar.com](http://www.sensofar.com)

Sales offices  
**SENSOFAR Asia**  
 Room 102, Building C -No.838, GUANGJI Road  
 HONGKOU District 200434 Shanghai (CHINA)  
 T: +86 21 61400058 F: +86 21 61400059  
 info.asia@sensofar.com

**SENSOFAR USA**  
 8655 E Via De Ventura Suite G168  
 Scottsdale, AZ 85258 (US)  
 Tel. 1 800 530 3097 Fax 419 745 1506  
 info@sensofarusa.com - [www.sensofarusa.com](http://www.sensofarusa.com)